

38
 (11) Non-Archimedean p-adic dynamics.

K alg closed complete metrized field non-trivial non-Archimedean

$\ell \in K[[T]] \quad \text{deg}(\ell) \geq 2.$

• Action on $A_K^{1,an}$

$x \in A_K^{1,an} \mapsto \ell(x)$ is the multiplicative semi-norm such that
 $\forall \phi \in K[[T]] \quad |\phi(\ell(x))| := |(\phi \circ \ell)(x)|.$

Lemma $x \mapsto \ell(x)$ is $B^{\circ,1}$ preserves the order relation, and is compatible with the natural map on K .

proof of $B^{\circ,1}$ fix $\ell \quad x_n \rightarrow x \in A_K^{1,an}$
 $|(\phi \circ \ell)(x_n)| \rightarrow |(\phi \circ \ell)(x)| \quad ! \quad //$

• Action on balls \rightarrow TVVP.

As in the complex domain

$\exists C \quad \left| \frac{1}{d} \text{Log}^+ |\ell| - \text{Log}^+ |x| \right| \leq C \quad (*)$

def: $x \in A_K^{1,an} \quad |x| := |T(x)|$

(*) is true for all $x \in K$ hence on $A_K^{1,an}$ by density. //

$\Rightarrow \quad \mathcal{G}_\ell = \liminf_{n \rightarrow \infty} \frac{1}{d^n} \text{Log}^+ |\ell^{d^n}| \geq 0, \mathcal{B}^P, \quad \mathcal{G}_\ell \circ \ell = d \mathcal{G}_\ell.$
 $\mathcal{G}_\ell = \text{Log} |z| + O(1)$ at infinity.

Def. $K(P) = \{ \mathcal{G}_\ell \geq 0 \}$ compact totally invariant
 $J(P) = d \cdot K(P)$ compact totally invariant.

Prop

- Take any 2 points $x, x' \in J(P)$
- $\{ y \leq x \} \subseteq K(P)$.
- $\{ y > x \} \subseteq \Omega(P) = A_K^{1,an} \setminus K(P)$
- if $x' \in J(P)$ then x & x' are not comparable

→ Action on balls: to compute the action of L , we rely on the following statement.

Lemma $n \geq 0$ $L(T) = \omega + a_1 T e^{-\dots} + \dots + a_d T^d$ $a_i \in K$.

$$\left[\begin{array}{l} \textcircled{1} L(\overline{B}(0, r)) = \overline{B}(\omega, \max_{1 \leq i \leq d} |a_i| r^i) = \overline{B}_1 \\ \textcircled{2} L(x_{\overline{B}(0, r)}) = x_{\overline{B}_1} \end{array} \right.$$

proof.

$$\textcircled{1} \Rightarrow \textcircled{2} \quad |(T-\alpha) L(x_{\overline{B}(0, r)})| = \sup_{\overline{B}(0, r)} |L(T)-\alpha|$$

$$= \sup_{L(\overline{B}(0, r))} |(T-\alpha)| = |(T-\alpha)(x_{\overline{B}_1})|.$$

$\textcircled{2}$ easy $L(\overline{B}(0, r)) \subseteq \overline{B}(\omega, \max |a_i| r^i)$.

to get the converse inclusion ~~we need to check~~

Let $\alpha = 0$ $n=1$ take $(z) \in \text{map}$ with

solve $L(z) = w = -w p a_1 T e^{-\dots} + \dots + a_d T^d$.

solutions z_1, \dots, z_d $|\sigma_d(z)| = \frac{|w|}{|a_d|}$ $|\sigma_{d-1}(z)| = \frac{|a_1|}{|a_d|}$

Abund $|z_i|$ for all i \Rightarrow $p = \max_{N \neq \# \{i \mid |z_i| = N\}}$

$|\sigma_N(z)| = p^N = \frac{|a_N|}{|a_d|} \geq |\sigma_d(z)| \geq p^N$ \parallel

40 proof. $x \mapsto \log^+ |P(x)|$ is increasing for \leq . (obvious!)

Hence g_P too as a uniform limit.

Pick $x \in J(P)$ $y \leq x$ then $g_P(y) > 0$ & $g_P(y) \geq g_P(x) = 0$.
 Pick $y > x$. if $g_P(y) > 0$ then $y \in \rightarrow (P)$. Otherwise $g_P(y) = 0$
 and the set $\{z, z < y\}$ is open and included in $\{g_P = 0\}$ outside $x \in \partial K(P)$. //

• Good reduction = special class of polynomial for which the dynamics reduces to \bar{K} .

def. $P = a_d T^d + \dots + a_0$ has good reduction if $a_i \in K^o$ and $\bar{P} = \sum \bar{a}_i T^i \in \bar{K}[T]$ has degree $= d$.
 [i.e. $|a_d| = 1 \geq \max_{0 \leq i < d} |a_i|$]

Thm $\left\{ \begin{array}{l} P \text{ has good reduction iff } P^{-1}(x_0) = x_0 \text{ iff } J(P) = \{x_0\} \text{ iff } \\ = aT^d + b \end{array} \right. \quad g_P = \log^+ |P|$

remark = it can be shown that

$\left\{ \begin{array}{l} \text{either } J(P) \text{ is reduced to one point and } \exists \phi \in \text{Aff}(\bar{K}) \\ \phi^{-1} \circ P \circ \phi \text{ has good reduction.} \\ \text{or } J(P) \text{ is a } G\text{-orbit set (and } h_{\text{top}}(P|_{J(P)}) > 0!). \end{array} \right.$

proof • P good reduction $\rightarrow P^{-1}(\bar{B}(0,1)) = \bar{B}(0,1)$ ~~if $|a_d| > 1$ then $P^{-1}(\bar{B}(0,1)) \subset \bar{B}(0,1)$~~
 • $|a_d| > 1 \Rightarrow |P(z)| = |a_d z^d + \dots|$ hence $P^{-1}(\bar{B}(0,1)) \subset \bar{B}(0,1)$
 • $z \in \bar{B}(0,1) \Rightarrow P(z) \in \bar{B}(0,1)$ then $\bar{B}(0,1) \subset P^{-1}(\bar{B}(0,1))$ in
obs $P(\bar{B}(0,1)) = \bar{B}(0,1)$ since K alg. closed

tho implies $\forall Q \quad |Q(P(x))| = |(Q \circ P)(x)| = \sup_{\bar{B}(0,1)} |Q(P(x))| = \sup_{\bar{B}(0,1)} |Q(z)| = \sup_{\bar{B}(0,1)} |Q(z)| = |Q(x_0)|$
 and $P(x_0) = x_0$.

4/

To get the total involution proceed as follows

if $P(x) = x^d$ then $|T(x)| \leq 1$ otherwise $|T(x)| > 1$ and
 $1 = |T(y)| = |P(x)| = \max_{i=1, \dots, d} |a_i| |T(x)|^i = |T(x)|^d > 1$.

Hence $x = \lim_{n \rightarrow \infty} x_{B_n}$ B_n decreasing balls $\{B_n\}$ included in $\overline{B(0,1)}$
 $|T(x)| \leq 1 \implies 1 = |(T^{-1})(x)| = |(P^{-1})(x)| \leq \sup_{B_n} |P^{-1}|$
 $= \sup_{B_n} |T^{-1}|$

if $\overline{B_n} = \overline{B}(z_n, r_n)$ and $r_n < 1$
 then $P(\overline{B_n}) = \overline{B}(P(z_n), r_n)$
 $P(T^{-1}z_n) = P(z_n) + \sum a_i T^i$ $r_n = \max |a_i| r_n^i \leq 1$.
 $|a_i| \leq 1 \implies \exists \alpha \sup_{P(\overline{B_n})} |T^{-1}| < 1$ absurd

Hence $P^{-1}(y) = y$.

• $P^{-1}(y) = y \implies$ good reduction

$P(y) = y^d \implies P(T) = a_0 + a_1 T + \dots + a_d T^d$ with $|a_i| \leq 1$ and at least one $i > 1$ s.t. $|a_i| = 1$. By contradiction, suppose $|a_d| < 1$.
 then $\exists r > 1$ $|a_d| r^d = \max_{1 \leq i \leq d} |a_i| r^i$. (> 1)

claim $\exists z$ $|z| = r$ and $P(z) = 0$.

$P(\overline{B}(z, \rho)) = \overline{B}(0, \rho)$ with $\theta: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ increasing and θ^p .
 $\theta(0) = 0$ and $\theta(r) = |a_d| r^d > 1$ hence $\exists r_0 < r$ s.t. $\theta(r_0) = 1$
 and $P(\overline{B}(z, r_0)) = \overline{B}(0, 1)$

proof of claim = pick z $|z|=r$ search for $|y|=1$ $P(yz) = 0$.
 $\varphi = a_0 + a_1 yz + a_2 y^2 z^2 + \dots + a_d y^d z^d = 0$
 $\implies a_0 + a_1 yz + a_2 y^2 z^2 + \dots + a_d y^d z^d = 0$
 $\implies a_0 + a_1 yz + a_2 y^2 z^2 + \dots + a_d y^d z^d = 0$
~~get a series for φ left to K so w .~~
 $\varphi(\overline{B}(w, \delta)) = \text{open ball of radius } \delta \text{ contains an element in } K^p \implies = B(0,1) //$

43

• $J(P) = \{x_3\} \Rightarrow \mathbb{L}^1(x_3) = x_3$

follows from the total invariance of $J(P)$

• Good reduction $\Rightarrow J(P) = \{x_3\}$

$\left. \begin{array}{l} |x_1| \leq 1 \\ |x_2| \leq 1 \end{array} \right\} \Rightarrow z \in K(P)$

$\left. \begin{array}{l} |x_1| > 1 \\ |x_2| > 1 \end{array} \right\} \Rightarrow z \in \mathbb{L}(P)$

• Good reduction $\Rightarrow g_{\mathbb{L}} = \text{Log}^P(b)$

$|x_1| \leq 1 \Rightarrow g_{\mathbb{L}} \in \mathbb{O}$

$|x_1| > 1 \Rightarrow |g_{\mathbb{L}}| = |a|^{d^m}$

$|g_{\mathbb{L}}| = |a|^{d \cdot d^m} = |a|^{d^{m+1}}$

• $g_{\mathbb{L}} = \text{Log}^P(b) \Rightarrow J(P) = \{x_3\}$

$K(P) = \{g_{\mathbb{L}} \in \mathbb{O}\} = \overline{B(0,1)}$