# Hydrodynamic Limits for the Boltzmann Equation 

François Golse
Université Paris 7 \& Laboratoire J.-L. Lions golse@math.jussieu.fr

Academia Sinica, Taipei, December 2004

## LECTURE 1

THE BOLTZMANN EQUATION: BASIC STRUCTURE

## Orders of magnitude, perfect gas

-For a monatomic gas at room temperature and atmospheric pressure, about $10^{20}$ gas molecules with radius $\simeq 10^{-8} \mathrm{~cm}$ are to be found in any volume of $1 \mathrm{~cm}^{3}$
-Excluded volume (i.e. the total volume occupied by the gas molecules if tightly packed): $10^{20} \times \frac{4 \pi}{3} \times\left(10^{-8}\right)^{-3} \simeq 5 \cdot 10^{-4} \mathrm{~cm}^{3} \ll 1 \mathrm{~cm}^{3}$

## EXCLUDED VOLUME NEGLIGEABLE $\Rightarrow$ PERFECT GAS

-Equation of state for a perfect gas:

$$
p=k \rho \theta, \text { where } k=\text { Boltzmann's constant }=1.38 \cdot 10^{-23} \mathrm{~J} / \mathrm{K}
$$

## Notion of mean-free path

-Roughly speaking, the average distance between two successive collisions for any given molecule in the gas
-There are more than one precise mathematical definitions of that notion (for instance, one can use the empirical measure to compute the mean)

- Intuitively, the higher the gas density, the smaller the mean-free path; likewise, the bigger the molecules, the smaller the mean-free path; this suggests

$$
\text { mean-free path } \approx \frac{1}{\mathcal{N} \times \mathcal{A}}
$$

where $\mathcal{N}=$ number of gas molecules per unit volume and $\mathcal{A}=$ area of the section of any individual molecule
-For the same monatomic gas as before (at room temperature and atmospheric pressure), $\mathcal{N}=10^{20}$ molecules $/ \mathrm{cm}^{3}$, while $\mathcal{A}=\pi \times\left(10^{-8}\right)^{2} \simeq$ $3 \cdot 10^{-16} \mathrm{~cm}^{2}$; hence the mean-free path is $\approx \frac{1}{3} \cdot 10^{-4} \mathrm{~cm} \ll 1 \mathrm{~cm}$.

## SMALL MEAN-FREE PATH REGIMES CAN OCCUR IN PERFECT GASES

-While keeping the same temperature, lower the pressure at $10^{-4} \mathrm{~atm}$; then $\mathcal{N}=10^{16}$ molecules $/ \mathrm{cm}^{3}$ and the mean-free path becomes $\approx \frac{1}{3} \mathrm{~cm}$ which is comparable to the size of the $1 \mathrm{~cm}^{3}$ container

DEGREE OF RAREFACTION MEASURED BY KNUDSEN NUMBER

$$
\mathrm{Kn}:=\frac{\text { mean free path }}{\text { macroscopic length scale }}
$$

## Kinetic vs. fluid regimes

- Fluid regimes are characterized by $\mathrm{Kn} \ll 1$; the gas is in local thermodynamic equilibrium: its state is adequately described by:
$p \equiv p(t, x)$ pressure, $\theta \equiv \theta(t, x)$ temperature, $\vec{u} \equiv \vec{u}(t, x)$ velocity field
- Kinetic regimes are characterized by $\mathrm{Kn}=O(1)$; since the gas is more rarefied, there are not enough collisions per unit of time for a local thermodynamic equilibrium to be reached. However, also because of rarefaction, correlations are weak $\Rightarrow$ state of the gas is adequately described by

$$
F \equiv F(t, x, v) \text { single-particle phase-space density }
$$

## Macroscopic observables

-One calls $F$ the "distribution function" or "number density"; $F(t, x, v)$ is the density (with respect to the Lebesgue measure $d x d v$ ) of particles which, at time $t$, are to be found at the position $x$ with velocity $v$.

- Macroscopic quantities (observables) are computed by averaging the corresponding quantity for a single particle w.r.t. the measure $F(t, x, v) d x d v$ :

$$
\text { momentum }=\iint m v F(t, x, v) d x d v, \text { energy }=\iint \frac{1}{2} m|v|^{2} F(t, x, v) d x d v
$$

-Likewise, one can also define macroscopic densities (w.r.t. the Lebesgue measure $d x$ ):

$$
\text { momentum density }=\int m v F(t, x, v) d v
$$

## The Boltzmann equation

-The number density $F$ is governed by the Boltzmann equation: in the absence of external force

$$
\partial_{t} F+v \cdot \nabla_{x} F=\mathcal{B}(F, F)
$$

where $\mathcal{B}(F, F)$ is the Boltzmann collision integral.

- Because of rarefaction, collisions other than BINARY are neglected.
-At the kinetic level of description, the size of particles is neglected everywhere but in the expression of the mean-free path: collisions are LOCAL and INSTANTANEOUS
$\Rightarrow \quad \mathcal{B}(F, F)$ operates only on the $v$-variable in $F$


## The collision integral (hard sphere gas)

-For a gas of hard spheres with radius $r$, Boltzmann's collision integral is

$$
\mathcal{B}(F, F)(v)=\iint_{\mathbf{R}^{3} \times \mathbf{S}^{2}}\left(F\left(v^{\prime}\right) F\left(v_{*}^{\prime}\right)-F(v) F\left(v_{*}\right)\right) r^{2}\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v_{*}
$$

where the velocities $v^{\prime}$ and $v_{*}^{\prime}$ are defined in terms of $v, v_{*}$ and $\omega$ by

$$
\begin{aligned}
v^{\prime} \equiv v^{\prime}\left(v, v_{*}, \omega\right) & =v-\left(v-v_{*}\right) \cdot \omega \omega \\
v_{*}^{\prime} \equiv v_{*}^{\prime}\left(v, v_{*}, \omega\right) & =v_{*}+\left(v-v_{*}\right) \cdot \omega \omega
\end{aligned}
$$

- Usual notation: $F_{*}, F^{\prime}$ and $F_{*}^{\prime}$ designate resp. $F\left(v_{*}\right), F\left(v^{\prime}\right)$ and $F\left(v_{*}^{\prime}\right)$


## Pre- to post-collision relations

- Given any velocity pair $\left(v, v_{*}\right) \in \mathbf{R}^{6}$, the pair $\left(v^{\prime}\left(v, v_{*}, \omega\right), v_{*}^{\prime}\left(v, v_{*}, \omega\right)\right)$ runs through the set of solutions to the system of 4 equations

$$
\begin{aligned}
v^{\prime}+v_{*}^{\prime} & =v+v_{*} & & \text { conservation of momentum } \\
\left|v^{\prime}\right|^{2}+\left|v_{*}^{\prime}\right|^{2} & =|v|^{2}+\left|v_{*}\right|^{2} & & \text { conservation of kinetic energy }
\end{aligned}
$$

as $\omega$ runs through $\mathrm{S}^{2}$.
-The geometric interpretation of these formulas is as follows: in the reference frame of the center of mass of the particle pair, the velocity pair before and after collisions is made of two opposite vectors, $\pm \frac{1}{2}\left(v^{\prime}-v_{*}^{\prime}\right)$ and $\pm \frac{1}{2}\left(v-v_{*}\right)$. Conservation of energy implies that $\left|v-v_{*}\right|=\left|v^{\prime}-v_{*}^{\prime}\right|$.

## Geometric interpretation of collision relations

- Hence $v-v_{*}$ and $v^{\prime}-v_{*}^{\prime}$ are exchanged by some orthogonal symmetry, whose invariant plane is orthogonal to $\pm \omega$.



## Symmetries of the collision integral

-The collision integrand is invariant if one exchanges $v$ and $v_{*}$ :

$$
\begin{aligned}
\int_{\mathbf{R}^{3}} \mathcal{B}(F, F) \phi d v & =\iiint\left(F^{\prime} F_{*}^{\prime}-F F_{*}\right) \phi\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v_{*} d v \\
& =\iiint\left(F^{\prime} F_{*}^{\prime}-F F_{*}\right) \frac{\phi+\phi_{*}}{2}\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v_{*} d v
\end{aligned}
$$

-The collision integrand is changed into its opposite if, given $\omega \in \mathbf{S}^{2}$, one exchanges ( $v, v_{*}$ ) and ( $v^{\prime}, v_{*}^{\prime}$ ) (in the center of mass reference frame, this is a symmetry, and thus an involution).
-Further, $\left(v, v_{*}\right) \mapsto\left(v^{\prime}, v_{*}^{\prime}\right)$ is an isometry of $\mathbf{R}^{6}$ (conservation of kinetic energy), so that $d v d v_{*}=d v^{\prime} d v_{*}^{\prime}$. Finally $\left(v-v_{*}\right) \cdot \omega=-\left(v^{\prime}-v_{*}^{\prime}\right) \cdot \omega$.

## Symmetries of the collision integral 2

Theorem. Assume that $F \in L^{1}\left(\mathbf{R}^{3}\right)$ is rapidly decaying at infinity, i.e.

$$
F(v)=O\left(|v|^{-n}\right) \text { as }|v| \rightarrow+\infty \text { for all } n \geq 0
$$

while $\phi \in C\left(\mathbf{R}^{3}\right)$ has at most polynomial growth at infinity, i.e.

$$
\phi(v)=O\left(1+|v|^{m}\right) \text { as }|v| \rightarrow+\infty \text { for some } m \geq 0
$$

Then, one has:

$$
\begin{aligned}
& \int_{\mathbf{R}^{3}} \mathcal{B}(F, F) \phi d v=\iiint F F_{*} \frac{\phi^{\prime}+\phi_{*}^{\prime}-\phi-\phi_{*}}{2}\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v_{*} d v \\
= & \iiint_{\mathbf{R}^{3} \times \mathbf{R}^{3} \times \mathbf{S}^{2}}\left(F^{\prime} F_{*}^{\prime}-F F_{*}\right) \frac{\phi+\phi_{*}-\phi^{\prime}-\phi_{*}^{\prime}}{4}\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v_{*} d v
\end{aligned}
$$

## Collision invariants

-These are the functions $\phi \equiv \phi(v) \in C\left(\mathbf{R}^{3}\right)$ such that

$$
\phi(v)+\phi\left(v_{*}\right)-\phi\left(v^{\prime}\right)-\phi\left(v_{*}^{\prime}\right)=0 \text { for all }\left(v, v_{*}\right) \in \mathbf{R}^{3} \text { and } \omega \in \mathbf{S}^{2}
$$

Theorem. Any collision invariant is of the form

$$
\phi(v)=a+b_{1} v_{1}+b_{2} v_{2}+b_{3} v_{3}+c|v|^{2}, \quad a, b_{1}, b_{2}, b_{3}, c \in \mathbf{R}
$$

- If $\phi$ is any collision invariant and $F \in L^{1}\left(\mathbf{R}^{3}\right)$ is rapidly decaying, then

$$
\int_{\mathbf{R}^{3}} \mathcal{B}(F, F) \phi d v=0
$$

## Local conservation laws

- In particular, if $F \equiv F(t, x, v)$ is a solution to the Boltzmann equation that is rapidly decaying in the $v$-variable

$$
\int_{\mathbf{R}^{3}} \mathcal{B}(F, F) d v=\int_{\mathbf{R}^{3}} v_{k} \mathcal{B}(F, F) d v=\int_{\mathbf{R}^{3}} \frac{1}{2}|v|^{2} \mathcal{B}(F, F) d v=0
$$

for $k=1,2,3$.
-Therefore, one has the local conservation laws:

$$
\begin{aligned}
\partial_{t} \int_{\mathbf{R}^{3}} F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v F d v & =0, \text { (mass) } \\
\partial_{t} \int_{\mathbf{R}^{3}} v F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v^{\otimes 2} F d v & =0, \text { (momentum) } \\
\partial_{t} \int_{\mathbf{R}^{3}} \frac{1}{2}|v|^{2} F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v \frac{1}{2}|v|^{2} F d v & =0, \text { (energy) }
\end{aligned}
$$

## Boltzmann's H Theorem

-Assume that $0<F \in L^{1}\left(\mathbf{R}^{3}\right)$ is rapidly decaying and such that $\ln F$ has polynomial growth at infinity. Then

$$
\begin{aligned}
& \int_{\mathbf{R}^{3}} \mathcal{B}(F, F) \ln F d v= \\
& -\frac{1}{4} \iiint_{\mathbf{R}^{3} \times \mathbf{R}^{3} \times \mathbf{S}^{2}}\left(F^{\prime} F_{*}^{\prime}-F F_{*}\right) \ln \left(\frac{F^{\prime} F_{*}^{\prime}}{F F_{*}}\right)\left|\left(v-v_{*}\right) \cdot \omega\right| d \omega d v d v_{*} \leq 0
\end{aligned}
$$

-The following conditions are equivalent:

$$
\int_{\mathbf{R}^{3}} \mathcal{B}(F, F) \ln F d v=0 \Leftrightarrow \mathcal{B}(F, F)=0 \text { a.e. } \Leftrightarrow F \text { is a Maxwellian }
$$

i.e. $F(v)$ is of the form

$$
F(v)=\mathcal{M}_{\rho, u, \theta}(v):=\frac{\rho}{(2 \pi \theta)^{3 / 2}} e^{-\frac{|v-u|^{2}}{2 \theta}} \text { for some } \rho, \theta>0 \text { and } u \in \mathbf{R}^{3}
$$

## $\mathcal{B}(F, F)=0$ implies $F$ is a Maxwellian

Lemma. (Perthame) Let $F>0$ a.e. be a measurable function s.t.

$$
\int\left(1+|v|^{2}\right) F(v) d v<+\infty
$$

If $F(v) F\left(v_{*}\right)=F\left(v^{\prime}\right) F\left(v_{*}^{\prime}\right)$ a.e. in $\left(v, v_{*}, \omega\right) \in \mathbf{R}^{3} \times \mathbf{R}^{3} \times \mathbf{S}^{2}$, then $F$ is a Maxwellian.
-WLOG, by translation and scaling, one can assume

$$
\int_{\mathbf{R}^{3}} F(v) d v=1, \quad \int_{\mathbf{R}^{3}} v F(v) d v=0
$$

-Apply the Fourier transform in $\left(v, v_{*}\right)$ to the equality satisfied by $F$ :

$$
\begin{aligned}
\hat{F}(\xi) \hat{F}\left(\xi_{*}\right) & =\iint e^{-i \xi \cdot v-i \xi_{*} \cdot v_{*}} F\left(v^{\prime}\right) F\left(v_{*}^{\prime}\right) d v d v_{*} \\
& =\iint e^{-i \xi \cdot v^{\prime}-i \xi_{*} \cdot v_{*}^{\prime}} F(v) F\left(v_{*}\right) d v d v_{*} .
\end{aligned}
$$

- In other words

$$
\widehat{F}(\xi) \widehat{F}\left(\xi_{*}\right)=\iint e^{-i \xi \cdot v-i \xi_{*} \cdot v_{*}} e^{i\left(\xi-\xi_{*}\right) \cdot \omega\left(v-v_{*}\right) \cdot \omega} F(v) F\left(v_{*}\right) d v d v_{*}
$$

Differentiate this in $\omega$ while keeping $\xi$ and $\xi_{*}$ fixed; at any $\omega_{0} \perp \xi-\xi_{*}$

$$
0=\iint e^{-i \xi \cdot v-i \xi_{*} \cdot v_{*}}\left(v-v_{*}\right) \cdot \omega_{0} F(v) F\left(v_{*}\right) d v d v_{*}
$$

- Hence, for each $\xi, \xi_{*} \in \mathbf{R}^{3}$

$$
\left(\nabla_{\xi}-\nabla_{\xi_{*}}\right) \widehat{F}(\xi) \hat{F}\left(\xi_{*}\right) \text { is colinear to } \xi-\xi_{*}
$$

$\bullet$ - In particular, for $\xi \neq 0$ and $\xi_{*}=0$, one has

$$
\nabla_{\xi} \widehat{F}(\xi) \text { is colinear to } \xi ;
$$

(notice that the assumptions on $F$ imply that $\hat{F} \in C^{2}\left(\mathbf{R}^{3}\right)$ ).

- In other words, the foliations of $\mathbf{R}^{3}$ by level surfaces of $\hat{F}$ and of $\frac{1}{2}|\xi|^{2}$ coincide. Hence there exists a function $f \in C^{1}\left(\mathbf{R}_{+}\right)$such that

$$
\widehat{F}(\xi) \text { is of the form } \widehat{F}(\xi)=f\left(|\xi|^{2}\right)
$$

- Going back to $\left(\nabla_{\xi}-\nabla_{\xi_{*}}\right) \hat{F}(\xi) \hat{F}\left(\xi_{*}\right)$, one sees that

$$
f^{\prime}\left(|\xi|^{2}\right) f\left(\left|\xi_{*}\right|^{2}\right) \xi-f\left(|\xi|^{2}\right) f^{\prime}\left(\left|\xi_{*}\right|^{2}\right) \xi_{*} \text { is colinear to } \xi-\xi_{*}
$$

Whenever $\xi$ and $\xi_{*}$ are not colinear, i.e. for a dense subset of $\mathbf{R}_{\xi}^{3} \times \mathbf{R}_{\xi_{*}}^{3}$ this last relation implies that

$$
f^{\prime}\left(|\xi|^{2}\right) f\left(\left|\xi_{*}\right|^{2}\right)=f\left(|\xi|^{2}\right) f^{\prime}\left(\left|\xi_{*}\right|^{2}\right)
$$

- Since $f$ is continuous, this relation holds everywhere on $\mathbf{R}_{\xi}^{3} \times \mathbf{R}_{\xi *}^{3}$; clearly, if $f^{\prime}$ vanishes somewhere, the above relation shows that $f$ must be a constant, hence $f=0$ since $\widehat{f}\left(|\xi|^{2}\right)$ is the Fourier transform of a $L^{1}$ function.
- Hence one can assume that $f^{\prime} \neq 0$ everywhere on $\mathbf{R}_{+}$; the relation above becomes

$$
\frac{f\left(|\xi|^{2}\right)}{f^{\prime}\left(|\xi|^{2}\right)}=\frac{f\left(\left|\xi_{*}\right|^{2}\right)}{f^{\prime}\left(\left|\xi_{*}\right|^{2}\right)} \Rightarrow \frac{f\left(|\xi|^{2}\right)}{f^{\prime}\left(|\xi|^{2}\right)}=\text { Const. }
$$

so that

$$
f(r)=e^{-\frac{1}{2} \alpha r}
$$

which in turn implies that

$$
\hat{F}(\xi)=e^{-\frac{1}{2} \alpha|\xi|^{2}}
$$

Hence $F$ is a Gaussian in $v$, as announced.

## Implications of conservation laws + H Theorem

- If $F \equiv F(t, x, v)>0$ is a solution to the Boltzmann equation that is rapidly decaying and such that $\operatorname{In} F$ has polynomial growth in the $v$ variable, then

$$
\begin{aligned}
\partial_{t} \int_{\mathbf{R}^{3}} F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v F d v & =0, \text { (mass) } \\
\partial_{t} \int_{\mathbf{R}^{3}} v F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v^{\otimes 2} F d v & =0, \text { (momentum) } \\
\partial_{t} \int_{\mathbf{R}^{3}} \frac{1}{2}|v|^{2} F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v \frac{1}{2}|v|^{2} F d v & =0, \text { (energy) } \\
\partial_{t} \int_{\mathbf{R}^{3}} F \ln F d v+\operatorname{div}_{x} \int_{\mathbf{R}^{3}} v F \ln F d v & \leq 0, \text { (entropy) }
\end{aligned}
$$

The last differential inequality bearing on the entropy density is reminiscent of the Lax-Friedrichs entropy condition that selects admissible solutions of hyperbolic systems of conservation laws.

## Fluctuation setup

Hydrodynamic limits of kinetic theory leading to incompressible flows consider solutions to the Boltzmann equation that are fluctuations of some uniform Maxwellian state.
-WLOG, we henceforth set this uniform equilibrium state to be

$$
M=\mathcal{M}_{(1,0,1)} \quad \text { (the centered, reduced Gaussian distribution) }
$$

-The size of the number density fluctuations around the equilibrium state $M$ will be measured in terms of the relative entropy defined as

$$
H(F \mid M)=\iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}}\left[F \ln \left(\frac{F}{M}\right)-F+M\right] d x d v \quad(\geq 0)
$$

for each measurable $F \geq 0$ a.e. on $\mathbf{R}^{3} \times \mathbf{R}^{3}$
-A formal computation shows that

$$
\begin{array}{r}
\frac{d}{d t} H(F \mid M)=\iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}} \partial_{t}\left[F \ln \left(\frac{F}{M}\right)-F+M\right] d x d v \\
=\iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}}\left(\partial_{t}+v \cdot \nabla_{x}\right)\left[F \ln \left(\frac{F}{M}\right)-F+M\right] d x d v \\
=\iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}} \ln \left(\frac{F}{M}\right)\left(\partial_{t}+v \cdot \nabla_{x}\right) F d x d v \\
=\iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}} \mathcal{B}(F, F) \ln F d x d v \leq 0
\end{array}
$$

since $\ln M$ is a collision invariant. This suggests that
$H(F(t) \mid M)$ is a nonincreasing function of $t$, and, for each $t>0$

$$
H(F(t) \mid M)-\int_{0}^{t} \iint_{\mathbf{R}^{3} \times \mathbf{R}^{3}} \mathcal{B}(F, F) \ln F d x d v=H(F(0) \mid M)
$$

